

**What is claimed is:**

1. A method for gray level dynamic switching, applied to a display with a pixel, comprising the following steps:  
providing a gray level sequence SG, wherein SG sequentially represents two or more desired gray levels  $G_o(1), \dots, G_o(T)$  of the pixel at consecutive time frames  $1, \dots, T$  and comprises a current gray level  $G_o(t)$  and a previous gray level  $G_o(t-1)$  corresponding to time frames  $t$  and  $t-1$ , respectively, and  $G_o(t)$  corresponds to a driving voltage  $V_o(t)$  to present  $G_o(t)$  under a static condition; and  
determining an optimized driving voltage  $V_d(t)$ , according to an equation  $V_d(t) = V_o(t-1) + ODV$ , wherein the ODV is a minimum voltage capable of obtaining one gray level transition in a determined response time;  
determining an dynamic gray level data  $G_d(t)$  according to an equation  $V_d(t) = a \times G_d(t)^3 + b \times G_d(t)^2 + c \times G_d(t) + d$ ;  
producing the optimized driving voltage  $V_d(t)$  according to the dynamic gray level data  $G_d(t)$ ;  
driving the pixel with optimized driving voltage  $V_d(t)$  to change the forward pixel to a state corresponding to  $G_o(t)$ .

2. The method as claimed in claim 1, wherein  $a$  is  $-0.0004$ ,  $b$  is  $0.0037$ ,  $c$  is  $-0.1443$ , and  $d$  is  $8.6992$ .

1           3. The method as claimed in claim 1, wherein, in  
2 positive frame, the polarity of the voltage ODV is positive  
3 when  $G_o(n) > G_o(n-1)$  and negative when  $G_o(n) < G_o(n-1)$ .

1           4. The method as claimed in claim 1, wherein, in  
2 negative frame, the polarity of the voltage ODV is negative  
3 when  $G_o(n) > G_o(n-1)$  and positive when  $G_o(n) < G_o(n-1)$ .

1           5. The method as claimed in claim 1, wherein the  
2 display is a liquid crystal display.

1           6. The method as claimed in claim 1, further comprising  
2 a step of adjusting the voltage ODV according to an operating  
3 temperature.

1           7. The method as claimed in claim 6, wherein the  
2 voltage ODV is inversely proportional to the operating  
3 temperature.

1           8. An apparatus for gray level dynamic switching,  
2 applied to drive a display with a pixel, comprising:

3           a memory set for storing a previous gray level  $G_o(t-1)$ ,  
4            $G_o(t-1)$  representing the desired gray level of the  
5           pixel at time frame  $t-1$ , and  $G_o(t-1)$  corresponding  
6           to a driving voltage  $V_o(t-1)$  to present  $G_o(t-1)$   
7           under a static condition;

8           a processor for determining an optimized driving voltage  
9            $V_d(t)$  according to a current gray level  $G_o(t)$  and  
10           an equation  $V_d(t) = V_o(t-1) + ODV$ , and determining an  
11           dynamic gray level data  $G_d(t)$  according to an  
12           equation  $V_d(t) = a \times G_d(t)^3 + b \times G_d(t)^2 + c \times G_d(t) + d$ ,  
13           wherein  $G_o(t)$  represents the desired level of the

14 pixel at time frame  $t$ , the voltage ODV is a minimum  
15 voltage capable of obtaining one gray level  
16 transition in a determined response time,  $a$  is  
17  $-0.0004$ ,  $b$  is  $0.0037$ ,  $c$  is  $-0.1443$ , and  $d$  is  $8.6992$ ;  
18 and  
19 a driving circuit for receiving  $G_d(t)$  and correspondingly  
20 generating the optimized driving voltage  $V_d(t)$  to  
21 drive the pixel to change the forward pixel to a  
22 current state corresponding to  $G_o(t)$ .

1 9. The apparatus as claimed in claim 8, wherein, in  
2 positive frame, the polarity of the voltage ODV is positive  
3 when  $G_o(t) > G_o(t-1)$  and negative when  $G_o(t) < G_o(t-1)$ .

1 10. The apparatus as claimed in claim 8, wherein, in  
2 negative frame, the polarity of the voltage ODV is negative  
3 when  $G_o(t) > G_o(t-1)$  and positive when  $G_o(t) < G_o(t-1)$ .

1 11. The apparatus as claimed in claim 8, wherein the  
2 processor further adjusts  $G_d(t)$  according to an operating  
3 temperature.

1 12. The apparatus as claimed in claim 11, wherein the  
2 voltage ODV is inversely proportional to the operating  
3 temperature.

1 13. The apparatus as claimed in claim 8, wherein the  
2 memory set is a set of dynamic random access memories (DRAM).

1 14. A display system, comprising:  
2 a display, having at least one pixel;  
3 a memory for storing a program;

a processor for executing, according to a program in the memory, the following steps:

receiving an original gray level sequence  $S_o$

consisting of two or more original gray levels

$G_o(1), \dots, G_o(T)$ , wherein a current gray level

$G_o(t)$  and a previous gray level  $G_o(t-1)$

correspond to time frames  $t$  and  $t-1$ ,

respectively, and  $G_o(t-1)$  corresponds to a

driving voltage  $V_o(t-1)$  to present  $G_o(t-1)$

under a static condition;

transforming  $S_o$  to an adjusted gray level sequence

$S_d$  consisting of two or more adjusted gray

levels  $G_d(1), \dots, G_d(M)$ , an adjusted gray level

$G_d(m)$  being generated according to a relevant

sub-sequence comprising  $G_o(t-1)$  and  $G_o(t)$ ,

wherein an optimized driving voltage  $V_d(t)$  is

determined according to the  $G_o(t)$  and an

equation  $V_d(t) = V_o(t-1) + ODV$ , and the adjusted

gray level  $G_d(m)$  is determined according to

an equation

$V_d(t) = a \times G_d(m)^3 + b \times G_d(m)^2 + c \times G_d(m) + d$ , wherein

the voltage ODV is a minimum voltage capable

of obtaining one gray level transition in a

determined response time,  $a$  is  $-0.0004$ ,  $b$  is

$0.0037$ ,  $c$  is  $-0.1443$ , and  $d$  is  $8.6992$ ; and

sequentially driving the pixel with driving forces

corresponding to  $G_d(1), \dots, G_d(M)$  in  $S_d$ .

1           15. The system as claimed in claim 14, wherein, in  
2 positive frame, the polarity of the voltage ODV is positive  
3 when  $G_o(t) > G_o(t-1)$  and negative when  $G_o(t) < G_o(t-1)$ .

1           16. The system as claimed in claim 14, wherein, in  
2 negative frame, the polarity of the voltage ODV is negative  
3 when  $G_o(t) > G_o(t-1)$  and positive when  $G_o(t) < G_o(t-1)$ .

1           17. The system as claimed in claim 14, wherein the  
2 program in the memory adjusts the  $G_d(m)$  according to an  
3 operating temperature.

1           18. The system as claimed in claim 17, wherein the  
2 voltage ODV is inversely proportional to the operating  
3 temperature.